

(1) Local frames.

Set of vector fields $(X_\mu)_{\mu=1,\dots,n}$ in $U \subset M$ is a frame in U
 if $\begin{cases} \text{smooth} \\ \text{open} \end{cases}$
 if $(X_\mu|_p)$ is a basis in $T_p(M) \quad \forall p \in U$.

Holonomic frame $(X_\mu) \Leftrightarrow [X_\mu, X_\nu] = 0 \quad \forall \mu, \nu = 1, \dots, n$

Holonomic frame (X_μ) in $U \subset M \Leftrightarrow \exists x^\mu$ in U s.t.
 $X_\mu = \frac{\partial}{\partial x^\mu}$

$\frac{\partial}{\partial x^\mu}$ and $A^\mu{}_\nu = A^\mu{}_\nu(x)$ invertible matrix-valued functions in U

$\Rightarrow X_\nu = A^\mu{}_\nu \frac{\partial}{\partial x^\mu}$ is in general nonholonomic.

(2) $\Lambda^s M$ -skew-symmetric smooth tensor fields of type (0_s)

$\Lambda^s M \ni \omega \Leftrightarrow \omega(x_1, \dots, x_i, \dots, x_j, \dots, x_s) = -\omega(x_1, \dots, x_j, \dots, x_i, x_s)$
 $\forall i < j$

~~defn~~ $d: \Lambda^s M \rightarrow \Lambda^{s+1} M$

$$\begin{aligned}
 d\omega(x_0, \dots, x_s) = & \sum_{i=0}^s (-1)^i x_i (\overset{x_i}{\omega}(x_0, \dots, \cancel{x_i}, \dots, x_s)) + \\
 & + \sum_{0 \leq i < j \leq s} (-1)^{i+j} \overset{x_i}{\omega}([x_i, x_j], x_0, \underset{i}{\cancel{\dots}}, \underset{j}{\cancel{\dots}}, x_s)
 \end{aligned}$$

Exterior differentiation

Check that $d\omega$ is f -linear!

In particular:

$$\boxed{d\omega(x, y) = x(\omega(y)) - y(\omega(x)) - \omega([x, y])}$$

③ Wedge product:

antisymmetrization

$$\text{Alt}_s : \mathcal{X}(M)_s^o \xrightarrow{\text{f-linear}} \mathcal{X}(M)^o_s$$

$$\text{Alt}_s(\omega_1 \otimes \dots \otimes \omega_s) = \frac{1}{s!} \sum_{\sigma \in S_s} \text{sgn}(\sigma) \omega_{\sigma(1)} \otimes \dots \otimes \omega_{\sigma(s)}$$

in particular:

$$\Lambda^s M \ni \omega : \text{Alt}_s(\omega) = \omega.$$

$$\overset{s}{\omega} \wedge \overset{t}{\omega} = \frac{(s+t)!}{s! t!} \text{Alt}_{s+t}(\overset{s}{\omega} \otimes \overset{t}{\omega}).$$

Ex

$$dx^u \wedge dx^v = \frac{(1+1)!}{1! 1!} \text{Alt}_{1+1}(dx^u \otimes dx^v)$$

$$= \frac{2!}{2!} (dx^u \otimes dx^v - dx^v \otimes dx^u)$$

④ Cartan algebra $(\Lambda M, \wedge, d)$

$$\Lambda M = \bigoplus_{s=0}^n \Lambda^s M, \quad \Lambda^0 M = \mathbb{F}(M)$$

⑤ Derivations of ΛM of degree k.

$$D : \Lambda M \longrightarrow \Lambda M \quad \text{s.t.}$$

$$D : \Lambda^s M \longrightarrow \Lambda^{s+k} M$$

$$D(\overset{s}{\omega} \wedge \overset{k}{\omega}) = D\overset{s}{\omega} \wedge \overset{k}{\omega} + (-1)^{sk} \overset{s}{\omega} \wedge D\overset{k}{\omega}.$$

Exempl. $d : \Lambda^k M \longrightarrow \Lambda M$ - derivation of degree +1

Example 2

$X(M) \otimes X$ defines derivation of degree -1. by

$$\begin{cases} X \lrcorner f = 0 \\ X \lrcorner df = X(f). \end{cases}$$

$$\begin{aligned} & (X \lrcorner \tilde{\omega})(x_1, \dots, x_s) \\ &= \tilde{\omega}(x_1, x_2, \dots, x_s) \end{aligned}$$

Locally $\omega = \frac{1}{s!} \omega_{\mu_1 \dots \mu_s} dx^{\mu_1} \wedge \dots \wedge dx^{\mu_s}$

$X \lrcorner \omega$ from the Leibnitz rule!

Example 3

$$\mathcal{L}_X = X \lrcorner d + d X \lrcorner$$

$$\Lambda^s M \longrightarrow \Lambda^s M$$

$$\mathcal{L}_X(\tilde{\omega} \wedge \tilde{\omega}) = \dots = \mathcal{L}_X^s \tilde{\omega} \wedge \tilde{\omega} + \tilde{\omega} \wedge \mathcal{L}_X^s \tilde{\omega}.$$

Example 4

$$\text{Locally } \tilde{\omega} = \frac{1}{2} \omega_{\mu\nu} dx^\mu \wedge dx^\nu = \frac{1}{2} \omega_{\mu\nu} (dx^\mu \otimes dx^\nu - dx^\nu \otimes dx^\mu)$$

$$\tilde{\omega}(X, Y) = \frac{1}{2} \omega_{\mu\nu} (X^\mu Y^\nu - X^\nu Y^\mu)$$

$$Y \lrcorner X \lrcorner \tilde{\omega} = Y \lrcorner X \lrcorner \left(\frac{1}{2} \omega_{\mu\nu} dx^\mu \wedge dx^\nu \right) =$$

$$= \frac{1}{2} \omega_{\mu\nu} Y \lrcorner (X^\mu dx^\nu - X^\nu dx^\mu) =$$

$$= \frac{1}{2} \omega_{\mu\nu} (X^\mu Y^\nu - X^\nu Y^\mu)$$

$$\begin{aligned} \tilde{\omega}(X, Y) &= (X \lrcorner \tilde{\omega})(Y) = \\ &= Y \lrcorner X \lrcorner \tilde{\omega} \end{aligned}$$

$$(X \lrcorner \tilde{\omega})(Y) =$$

$$= \frac{1}{2} \omega_{\mu\nu} (X^\mu dx^\nu - X^\nu dx^\mu)(Y)$$

$$= \frac{1}{2} \omega_{\mu\nu} (X^\mu Y^\nu - X^\nu Y^\mu)$$

(OK)

$$X_{k-1} \lrcorner \dots \lrcorner X_1 \lrcorner \tilde{\omega} = \tilde{\omega}(X_1, \dots, X_k)$$

$$Y \lrcorner X \lrcorner \tilde{\omega} = \tilde{\omega}(X, Y)$$

⑥ Maurer-Cartan theorem

4

X_μ - frame in U

$$[X_\mu, X_\nu] = c^\delta_{\mu\nu} X_\delta \quad \text{smooth}$$

$c^\delta_{\mu\nu}$ are functions in U .

$$c^\delta_{\mu\nu} = -c^\delta_{\nu\mu}$$

$c^\delta_{\mu\nu} = 0$ in $U \Leftrightarrow$ ~~exists~~ local coord. system s.t.

$$X_\mu = \frac{\partial}{\partial x^\mu}$$

ω^μ is a coframe dual to X_μ in U iff

$$X_\mu \lrcorner \omega^\nu = \omega^\nu(X_\mu) = \delta_\mu^\nu.$$

Then

$$[X_\mu, X_\nu] = c^\delta_{\mu\nu} \Leftrightarrow d\omega^\mu = \frac{1}{2} c^\mu_{\alpha\beta} \omega^\alpha \wedge \omega^\beta$$

Proof

$$X_\rho \lrcorner X_\nu \lrcorner d\omega^\mu = d\omega^\mu(X_\nu, X_\rho) = X_\nu(\cancel{\omega^\mu(X_\rho)}) - X_\rho(\cancel{\omega^\mu(X_\nu)}) - \tilde{\omega}([X_\nu, X_\rho]) =$$

$$= -c^\mu_{\nu\rho}$$

$$X_\rho \lrcorner X_\nu \lrcorner (-\frac{1}{2} c^\mu_{\alpha\beta} \omega^\alpha \wedge \omega^\beta) = \frac{1}{2} X_\rho \lrcorner (-c^\mu_{\nu\beta} \omega^\beta + c^\mu_{\alpha\nu} \omega^\alpha) =$$

$$= -\frac{1}{2}(c^\mu_{\nu\rho} + c^\mu_{\rho\nu}) = -c^\mu_{\nu\rho}$$

$$\boxed{d\omega^\mu = -\frac{1}{2} c^\mu_{\alpha\beta} \omega^\alpha \wedge \omega^\beta}$$

□.

② Föbenius revisited

S -distribution

$$S^* = \{ \omega \in \Lambda^1 M : \omega(x) = 0 \quad \forall x \in S \}$$

$(X_i)_{i=1, \dots, m}$ frame for S $i, j, k, \dots = 1, \dots, m$

$(\omega^\alpha)_{\alpha=m+1, \dots, n}$ frame for S^* $\alpha, \beta, \gamma, \dots = m+1, \dots, n$

The following conditions are equivalent:

1) Through every point $p \in M$ passes precisely one integral manifold of S

$\Leftrightarrow 2) [X_i, X_j] = C^k{}_{ij} X_k$

$3) \quad X_i = A^j{}_i (x^\kappa, x^\delta) \frac{\partial}{\partial x_j}$

$4) \quad d\omega^\alpha \wedge \omega^{m+1} \wedge \dots \wedge \omega^n = 0 \quad \forall \alpha = m+1, \dots, n$

$5) \quad \omega^\alpha = B^\alpha_\beta (x^\kappa, x^\delta) dx^\beta$

Proof

1) \Leftrightarrow 2) \checkmark

3) \Rightarrow 5) since $X_i \perp \omega^\alpha = 0$ and $\dim S^* = n-m$

5) \Rightarrow 4) obvious

4) \Rightarrow 2) $d\omega^\alpha = -\frac{1}{2} C^\alpha{}_{\beta\gamma} \omega^\beta \wedge \omega^\gamma - \frac{1}{2} C^\alpha{}_{ijk} \overset{(A)}{\cancel{\omega^i}} \wedge \overset{(B)}{\cancel{\omega^j}} - \frac{1}{2} C^\alpha{}_{i\beta} \omega^i \wedge \omega^\beta$

$$[X_i, X_j] = C^k{}_{ij} X_k + C^\alpha{}_{ij} \cancel{\omega_\alpha}$$

□.

Rank q of a 2-form α is defined by:

$$\underbrace{dx \wedge \dots \wedge dx}_{q\text{-times}} \neq 0$$

$$\underbrace{dx \wedge \dots \wedge dx}_{(q+1)\text{-times}} = 0$$

$$2q \leq n$$

Darboux theorem

① Let σ be a 1-form s.t. $d\sigma$ has rank $2q$.

Then there exist local coordinates

$x^1, \dots, x^q, y^1, \dots, y^{n-q}$ s.t.

$$\sigma = \begin{cases} x^1 dy^1 + \dots + x^q dy^q & \text{if } \sigma \wedge d\sigma \wedge \dots \wedge d\sigma \underset{q\text{-times}}{=} 0 \\ x^1 dy^1 + \dots + x^q dy^q + dy^{q+1} & \text{if } \sigma \wedge d\sigma \wedge \dots \wedge d\sigma \underset{q\text{-times}}{\neq} 0 \end{cases}$$

② For any 2-form α of rank q there exists a basis (ω^α) such that

$$\alpha = \omega^1 \wedge \omega^2 + \omega^3 \wedge \omega^4 + \dots + \omega^{2q-1} \wedge \omega^{2q}$$

If $d\alpha = 0$ then there exist coordinates $x^1, \dots, x^q, y^1, \dots, y^{n-q}$

$$\alpha = dx^1 \wedge dy^1 + \dots + dx^q \wedge dy^q$$

Proof Sternberg S (1964)

Lectures on differential geometry (Prentice-Hall, Englewood Cliffs, NJ)